

Name: [5 pts]

1) A uniform rod with mass  $m$  and length  $r_1 + r_2$  is pivoted at a point. Ignore gravity or assume all the motions are happening on a horizontal plane, i.e. looking from above systems looks like fig. 1. At a distance  $r_1$  from this rod, there is a spring connected to rod with constant  $k_1$ , and at a distance  $r_2$  there is another spring connected to the rod with constant  $k_2$ . See fig. 1. All the motion can be explained by one degree of freedom  $\theta$ . Also assume  $\sin \theta \approx \theta$  and  $\cos \theta \approx 1$ .

- a) In terms of  $\theta$ , find the spring forces. [2 pts]
- b) Find the torque, about the pivot point, in terms of  $\theta$ . [3 pts]
- c) Prove that  $I_p = m(r_1^2 + r_2^2 - r_1 r_2)/3$  where  $p$  is the pivot point. [2 pts]
- d) Find the frequency of the small oscillations. [3 pts]
- e) Write down a formula for the mechanical energy, in terms of  $\theta$  and  $\dot{\theta}$ . What is the effective "mass" and effective "spring constant" for the parameter  $\theta$ ? [2 pts]

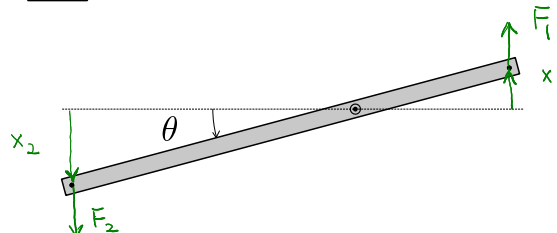
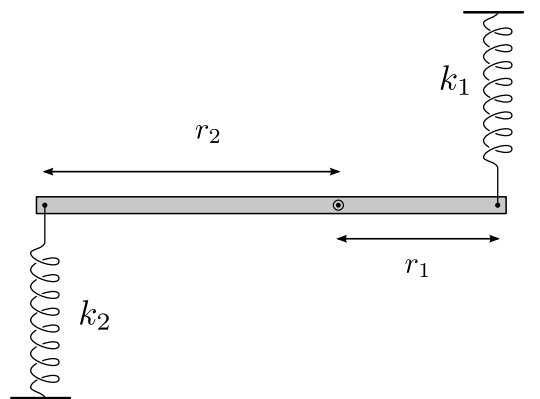


Figure 1: A rod pivoted to a point and connected to springs. I drew the rod again at an angle  $\theta$ .

a)  $x_1 = r_1 \theta$        $F_1 = -k_1 x_1 = -k_1 r_1 \theta$   
 $x_2 = r_2 \theta$        $F_2 = -k_2 x_2 = -k_2 r_2 \theta$

b)  $\tau = F_1 r_1 + F_2 r_2$   
 $= -(k_1 r_1^2 + k_2 r_2^2) \theta$

c) Parallel axis thm:  
 $I_{cm} = \frac{1}{12} m(r_1 + r_2)^2$

$$I_p = I_{cm} + m \left( \frac{r_1 - r_2}{2} \right)^2 = m \left[ \frac{r_1^2 + r_2^2 + 2r_1 r_2}{12} + \frac{r_1^2 + r_2^2 - 2r_1 r_2}{4} \right]$$

$$= m \frac{4r_1^2 + 4r_2^2 - 4r_1 r_2}{12} = \frac{1}{3} m(r_1^2 + r_2^2 - 2r_1 r_2).$$

d)  $\tau = I_p \ddot{\theta} \rightarrow -(k_1 r_1^2 + k_2 r_2^2) \theta = I_p \ddot{\theta} \rightarrow \ddot{\theta} + \frac{k_1 r_1^2 + k_2 r_2^2}{I_p} \theta = 0$

so  $\omega = \left[ \frac{k_1 r_1^2 + k_2 r_2^2}{\frac{1}{3} m(r_1^2 + r_2^2 - r_1 r_2)} \right]^{1/2}$ .

e)  $E = U + K = \frac{1}{2} k_1 x_1^2 + \frac{1}{2} k_2 x_2^2 + \frac{1}{2} I_p \dot{\theta}^2 = \frac{1}{2} (k_1 r_1^2 + k_2 r_2^2) \theta^2 + \frac{1}{2} I_p \dot{\theta}^2$

$K_{eff} = k_1 r_1^2 + k_2 r_2^2, \quad M_{eff} = I_p.$